

Stable droplets and growth laws close to the modulational instability of a domain wall

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We consider the curvature driven dynamics of a domain wall separating two equivalent states in systems displaying a modulational instability of a flat front. We derive an amplitude equation for the dynamics of the curvature close to the bifurcation point from growing to shrinking circular droplets. We predict the existence of stable droplets with a radius R that diverges at the bifurcation point, where a curvature driven growth law $R(t) \approx t^{1/4}$ is obtained. Our general analytical predictions, which are valid for a wide variety of systems including models of nonlinear optical cavities and reaction-diffusion systems, are illustrated in the parametrically driven complex Ginzburg-Landau equation.

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Growth of spatial domains of different phases in the transient regime of a system approaching thermodynamic equilibrium has been studied long ago [1]. This phenomenon is a prototype of nonlinear dynamics of an extended system governed by the motion of domain walls. Power laws for the growth of a characteristic size and self-similar evolution (dynamical scaling) have been established. Clear physical mechanisms explaining the different asymptotic growth laws have also been identified [1]. It is convenient to consider domain growth in systems with conserved and non-conserved order parameters separately. In the first case one talks of spinodal decomposition leading to the Lifshits-Slyozov $t^{1/3}$ power law. In the case of non-conserved order parameters, the dominant mechanism is curvature driven minimization of surface tension, leading to the Allen-Cahn (AC) $t^{1/2}$ power law [2].

The study of domain growth and domain wall motion in non-equilibrium systems that do not approach thermodynamic equilibrium is by far more complicated. There is presently only a partial understanding of a variety of possible situations [3,4]. In particular a number of results have been recently reported for domain growth and domain wall motion in the transverse plane of nonlinear optical systems [5–9]. However, these numerical results often fail to identify the physical mechanism responsible for the observed dynamics. Moreover, the power laws for domain growth do not always correspond unambiguously to an asymptotic and self-similar dynamics. An exception is the $t^{1/2}$ law obtained for two different optical systems for which evidence of dynamical scaling has been given [6,7]. Visual inspection of the time dependent configurations clearly indicate curvature driven domain wall dynamics, but no derivation of such a law has been given for these systems. Surface tension, whose minimization may be used to explain the AC law, is not an appropriate concept for these optical systems.

In this letter we analyze the transition from a regime

characterized by a $t^{1/2}$ growth law to one of labyrinthine pattern formation due to a modulational instability of a flat domain wall connecting two equivalent homogeneous solutions. Such a transition from coarsening to labyrinthine regimes has been observed experimentally in reaction-diffusion [10] and in optical [11] systems, and numerically in [6], as well as in Swift-Hohenberg models [12]. At difference with systems approaching thermodynamic equilibrium, the coefficient of the $t^{1/2}$ power law can now change sign upon variations of a control parameter p at $p = p_c$. For $p < p_c$ ($p > p_c$) a circular domain of radius R of one solution embedded in the other grows (shrinks as in the AC regime) as $R(t) = \sqrt{R(0) - \gamma t}$ with $\gamma < 0$ ($\gamma > 0$). Moreover, for $p < p_c$ a flat front is modulationally unstable and a generic initial condition develops in a labyrinthine pattern. Close to the modulational instability at p_c we derive an amplitude equation for the curvature of circular domains. At p_c a circular domain grows as $R(t) \sim t^{1/4}$. For p larger but close to p_c an initially small (very large) domain grows (shrinks) until a stable droplet (SD) is formed. The radius of the SD diverges at p_c . The SD should not be confused with other types of soliton-like localized structures (LS) appearing in the AC regime when the front oscillatory tail prevents the domain collapse [7,13,6]. The SD are also different from the critical nucleus of nucleation theory [1] where the droplet is unstable and inner and outer solutions are not equivalent. Note also that droplets found in reaction-diffusion systems [14] involve two non equivalent states.

Our analytical results are illustrated by considering a prototypical model, the parametrically driven complex Ginzburg-Landau equation (PCGLE) [15,16], which describes a oscillatory system parametrically forced at twice its natural frequency [10]:

$$\begin{aligned} \partial_t A = (1 + i\alpha)\nabla^2 A + (\mu + i\nu)A \\ - (1 + i\beta)|A|^2 A + pA^*, \end{aligned} \quad (1)$$

where μ measures the distance from the oscillatory insta-

bility threshold, ν is the detuning parameter and $p > 0$ is the forcing amplitude. For $p \sim \nu \sim \alpha$ large compared to other parameters, a finite wavelength instability forming hexagons takes place for $p < p_h$, while for $p > p_h$ there are two equivalent stable homogeneous solutions (frequency locked solutions) [16].

We consider a real N component vector field $\vec{\Psi}(\vec{x})$ whose dynamical evolution in two spatial dimensions is

$$\partial_t \vec{\Psi} = D \nabla^2 \vec{\Psi} + \vec{W}(\vec{\Psi}, p), \quad (2)$$

where the matrix D describes the spatial coupling, \vec{W} is a local nonlinear function of the fields and p a control parameter. Eq. (2) is invariant under translations and under the change $\vec{x} \rightarrow -\vec{x}$. In addition we assume that it has a discrete symmetry \mathcal{Z} that allows for the existence of two, and only two, equivalent stable homogeneous solutions, and that, in a 1d system, they are connected by a stable Ising front $\vec{\Psi}_0(x, p)$. An Ising front satisfies $\vec{\Psi}_0(x_0 - x) = \mathcal{Z} \vec{\Psi}_0(x - x_0)$ where x_0 is the front location [17], thus the 1d front (and equivalently a flat front in 2d) is stationary, $D \nabla^2 \vec{\Psi}_0 + \vec{W}(\vec{\Psi}_0, p) = 0$. For the PCGLE $\vec{\Psi}(\vec{x}) = (\text{Re}[A(\vec{x})], \text{Im}[A(\vec{x})])$, $D = ((1, \alpha)^T, (-\alpha, 1)^T)$, $\vec{\Psi}_0(x)$ describes a flat front connecting the two homogeneous solutions (we consider $p > p_h$) and $\mathcal{Z} = -I$ where I is the identity matrix.

Let $\vec{X}(s, t)$ represent the instantaneous position vector of the front in the \vec{x} plane, where s is the arclength. It is convenient to define a coordinate system (r, s) that moves with the front such that $\vec{x} = \vec{X}(s, t) + r \hat{r}(s, t)$, where \hat{r} is a unit vector normal to the curve \vec{X} and the coordinate r is the distance of the point \vec{x} to the front [3]. In the moving frame Eq. (2) becomes

$$D \partial_r^2 \vec{\Psi} + \left(vI + \frac{\kappa}{1 + r\kappa} D \right) \partial_r \vec{\Psi} + \frac{\kappa^2 D \partial_\theta^2 \vec{\Psi}}{(1 + r\kappa)^2} + \vec{W}(\vec{\Psi}, p) = \partial_t \vec{\Psi}, \quad (3)$$

where $v = \partial_t \vec{X} \cdot \hat{r}$ is the (normal) front velocity and $\theta = \kappa s$ is the azimuthal angle. We analyze the dynamics of slightly curved fronts as a perturbation of the flat front $\vec{\Psi}(r, s, t) = \vec{\Psi}_0(r) + \vec{\Psi}_1(r, s, t)$. We assume that i) $\kappa w \ll 1$, with $\kappa = \nabla \cdot \hat{r}$ the curvature and w the front width, ii) in the moving frame the front profile depends at most weakly on t ($|\partial_t \vec{\Psi}| \ll |\kappa D \partial_r \vec{\Psi}|$) and iii) κ is a function which depends at most weakly on s , thus $|\kappa \partial_\theta^2 \vec{\Psi}| \ll |\partial_r \vec{\Psi}|$. Linearizing around $\vec{\Psi}_0$ we have

$$M \vec{\Psi}_1 = -(vI + \kappa D) \partial_r \vec{\Psi}_0, \quad (4)$$

where $M_j^i = D_j^i \partial_r^2 + \delta_{\Psi j} W^i|_{\vec{\Psi}_0, p}$. Due to the translational invariance of (2) M is singular, $M \vec{e}_0 = 0$ where $\vec{e}_0 \equiv \partial_r \vec{\Psi}_0$ is the Goldstone mode. The solvability condition applied to (4) leads to $v = -\gamma(p)\kappa$, where

$$\gamma(p) \equiv \frac{1}{\Gamma} \int_{-\infty}^{\infty} \vec{a}_0 \cdot D \vec{e}_0 dr, \quad (5)$$

$\Gamma \equiv \int_{-\infty}^{\infty} \vec{a}_0 \cdot \vec{e}_0 dr$ [18] and \vec{a}_0 is the null mode of M^\dagger . For a circular domain $\kappa = 1/R$ and

$$v = \dot{R} = -\gamma(p)/R. \quad (6)$$

From Eq. (4) one obtains that the perturbation of the front, $\vec{\Psi}_1(r, t) = \kappa(t) \vec{\varphi}_1(r)$, is independent of s while the dependence on t comes only through the curvature. $\vec{\varphi}_1$ satisfies

$$M \vec{\varphi}_1 = -(-\gamma I + D) \vec{e}_0. \quad (7)$$

For systems such that the diffusion matrix is proportional to the identity, $D = dI$, γ takes the constant value d independently of the profile of the front and any system parameter. In this case, the rhs of (7) vanishes and $\vec{\varphi}_1$ must be either zero or proportional to the Goldstone mode \vec{e}_0 . Physically this means that the fronts translate without changing their radial profile. The front velocity is proportional to the curvature with opposite sign $v = -d\kappa$, which is the well known AC law [1,2]. This law implies a coarsening regime with a $t^{1/2}$ growth law and shrinking of circular domains.

In general, $D = dI + C$ with a non zero matrix C . C leads to a contribution to γ that depends on the profile of the front $\vec{\Psi}_0$ and therefore, on the system parameters. From Eq. (7) we have that $\vec{\varphi}_1$ is no longer proportional to the Goldstone mode. This means that the transverse profile of the front is now deformed. Since $\vec{\Psi}_1(r, t) = \kappa(t) \vec{\varphi}_1(r)$, the amount of deformation is proportional to the curvature and C . The d contribution is generally positive and, for wide parameter regions, γ is also positive. Here flat walls are stable and the AC law still applies [6,7]. Circular domains shrink but the presence of oscillatory tails in the front may prevent the droplet to disappear forming a LS as found in nonlinear optical cavities [7,13,6].

The crucial point is that for some parameter values the contribution to γ due to C may be negative and larger than d . γ changes sign and a bifurcation occurs. This is particularly relevant in nonlinear optical systems where the spatial coupling is diffractive and $d = 0$. For $\gamma < 0$ the velocity has the same sign of the curvature leading to the growth of any perturbation of the flat wall. The condition for vanishing γ , $\int_{-\infty}^{\infty} \vec{a}_0 \cdot D \vec{e}_0 dr = 0$, is in fact the criterion for the modulational instability of a flat front. Modulational instabilities in fronts connecting two equivalent homogeneous states have been observed in different systems [6,8]. Starting from a random initial condition, the system develops labyrinthine patterns [6,10]. Also, a circular domain of radius R grows like (6) until its boundary breaks up because of the modulational

instability leading to the formation of a labyrinthine pattern.

In Fig. 1 we show the value of γ for the PCGLE calculated using definition (5), with the profile of the 1d front calculated numerically by solving the stationary form $\partial_t A = 0$ in 1d of (1). This calculation identifies p_c for which $\gamma = 0$.

We are now ready to obtain an amplitude equation for the curvature in the vicinity of p_c . We start considering the case of a circular domain wall (for which $v = -\dot{\kappa}/\kappa^2$). Close to p_c ($\gamma \approx 0$) we perform a multiple scale analysis in ϵ of Eq. (3) with $p = p_c + \epsilon p_1$, $\vec{\Psi} = \vec{\Psi}_0 + \epsilon^{1/2} \vec{\Psi}_1 + \epsilon \vec{\Psi}_2 + \epsilon^{3/2} \vec{\Psi}_3$, $\kappa = \epsilon^{1/2} \kappa_1$ and $\partial_t = \epsilon^2 \partial_T$. At order $\epsilon^{1/2}$ we obtain $M \vec{\Psi}_1 = -\kappa_1 D \vec{e}_0$. The solvability condition implies $\int_{-\infty}^{\infty} \vec{a}_0 \cdot D \vec{e}_0 dr = 0$, which is automatically satisfied at $p = p_c$. One finds $\vec{\Psi}_1 = \kappa_1 \vec{\varphi}_1$ where $\vec{\varphi}_1$ satisfies $M \vec{\varphi}_1 = -D \vec{e}_0$. Due to the symmetry of the front the solvability condition at order ϵ is always fulfilled and we get $\vec{\Psi}_2 = p_1 \vec{\varphi}_2 + \kappa_1^2 \vec{\varphi}_3$ with $M \vec{\varphi}_2 = -\partial_p \vec{W}|_0$ and $M \vec{\varphi}_3 = -D_j^i (\partial_r \varphi_1^j - r e_0^j) - \frac{1}{2} \delta_{\Psi^j \Psi^k} W^i|_0 \varphi_1^j \varphi_1^k$ where $|_0$ means evaluated at $\vec{\Psi}_0$ and p_c . At order $\epsilon^{3/2}$, the amplitude equations for the curvature κ_1 and the radius of the circular droplet

$$\frac{\partial_T \kappa_1}{\kappa_1^2} = c_1 p_1 \kappa_1 + c_3 \kappa_1^3 \quad (8)$$

$$\partial_t R = -c_1(p - p_c) \frac{1}{R} - c_3 \frac{1}{R^3} \quad (9)$$

where

$$c_1 = \frac{1}{\Gamma} \int_{-\infty}^{\infty} a_{0i} (D_j^i \partial_r \varphi_2^j + \delta_{\Psi^j \Psi^k} \partial_p W^i|_0 \varphi_1^j + \delta_{\Psi^j \Psi^k} W^i|_0 \varphi_1^j \varphi_2^k) dr \quad (10)$$

$$c_3 = \frac{1}{\Gamma} \int_{-\infty}^{\infty} a_{0i} [D_j^i (\partial_r \varphi_3^j - r \partial_r \varphi_1^j + r^2 e_0^j) + \delta_{\Psi^j \Psi^k} W^i|_0 \varphi_1^j \varphi_3^k + \frac{1}{6} \delta_{\Psi^j \Psi^k \Psi^l} W^i|_0 \varphi_1^j \varphi_1^k \varphi_1^l] dr \quad (11)$$

are obtained from the solvability condition. The coefficient c_1 is positive since $\gamma = c_1(p - p_c)$, and we are considering $\gamma > 0$ for $p > p_c$. If c_3 is negative (super-critical bifurcation) our analysis predicts just above the modulational instability the existence of stable stationary circular domains (SD) with a very large radius

$$R_0 = \frac{1}{\sqrt{p - p_c}} \sqrt{\frac{-c_3}{c_1}}. \quad (12)$$

In Fig. 2 (left) we show the form of the SD for the PCGLE. At the center the field takes the value of one of the homogeneous solutions, so the wall of this structure is a heteroclinic orbit between the two homogeneous states. The radius of the SD can be extremely large diverging at $p = p_c$. Fig. 2 (right) displays the radius of

the SD and that of the LS calculated solving numerically $(1+i\alpha)(\partial_r^2 + \frac{1}{r} \partial_r)A + (\mu + i\nu)A - (1+i\beta)|A|^2 A + pA^* = 0$. The inset in Fig. 2 (right) shows the linear dependence of $1/R_0^2$ with p as predicted by (12). In spite of the fact that there is a smooth transition from LS to SD, they are intrinsically different. The interaction of the oscillatory tails which is responsible for the existence of LS does not play any role in the SD. The stabilization mechanism comes from the counterbalance between the R^{-3} contribution to the front velocity and the shrinking due to the R^{-1} contribution.

At the bifurcation point $p = p_c$, Eq. (9) becomes $\partial_t R = -c_3/R^3$ and any circular domain of one solution embedded in the other grows as $R(t) \sim t^{1/4}$. In Fig. 3 we show the time evolution of the radius of a circular domain for the PCGLE at $p = p_c$. It fits nicely the theoretical dependence we predict. Close to p_c , in the regime of existence of the SD, there is no asymptotic power law of domain growth since at very long times the SD is formed stopping the growth process. During the transient, an initially small (very large) circular domain will grow (shrink) following (9).

So far we have considered the dynamics of domains with radial symmetry. When the system evolves from random initial conditions other dynamical mechanisms come into play. Close to the bifurcation point the main non-radially symmetric contribution to the velocity comes from the variation of the curvature along the front. The derivation of the amplitude equation for the curvature leads to an additional term in Eq. (8) $c_2 \kappa_1^2 \partial_\theta^2 \kappa_1$ where $c_2 = \frac{1}{\Gamma} \int_{-\infty}^{\infty} \vec{a}_0 \cdot D \vec{\varphi}_1 dr$. The front velocity becomes $v = -c_1(p - p_c)\kappa - c_2 \kappa^2 \partial_\theta^2 \kappa - c_3 \kappa^3$. Consistently with our approximations, $\partial_\theta^2 \kappa$ will change at most at order κ^0 , so the non-radial contribution is at least of order κ^2 . Close to the bifurcation point the term proportional to κ can be neglected, and the term given by $-c_2 \kappa^2 \partial_\theta^2 \kappa$ might be dominant compared with the one proportional to κ^3 . In this case the front velocity is proportional to κ^2 . However, for any closed boundary $\partial_\theta^2 \kappa$ is positive in some parts of the wall and negative in others, so this term does not lead to an asymptotic growth law. For $c_2 < 0$, which is the case for the PCGLE, this term tends to reduce the curvature differences, so at p_c an arbitrarily shaped domain first becomes circular until the contribution of $\partial_\theta^2 \kappa$ vanishes and then the circular domain grows as $R(t) \sim t^{1/4}$ due to the c_3 term (see Fig. 4).

In summary, we have analyzed a generic situation of domain wall motion driven by curvature effects in which the proportionality coefficient γ between wall velocity and curvature changes sign at a bifurcation point. In optical systems, this change is a consequence of the diffractive coupling between real and imaginary parts of the complex field amplitude. The amplitude equation for the curvature in the vicinity of the bifurcation point pre-

dicts the existence of stable nonlinear solutions which are droplets of one phase embedded in a background of the second equivalent phase. Nonlinear dynamics of the curvature leads to growth laws different from the AC $t^{1/2}$ -growth law. The existence of a large characteristic length given by the radius of the SD destroys the possibility of self-similar evolution.

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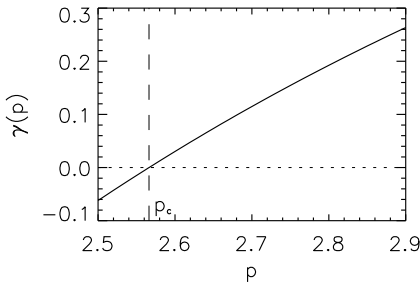


FIG. 1. Value of the γ as a function of the forcing amplitude p for the PCGLE calculated from (5). We take here $\alpha = 2$, $\beta = 0$, $\nu = 2$ and $\mu = 0$. For these values of the parameters $p_h = 2.09$ and $p_c = 2.56629$.

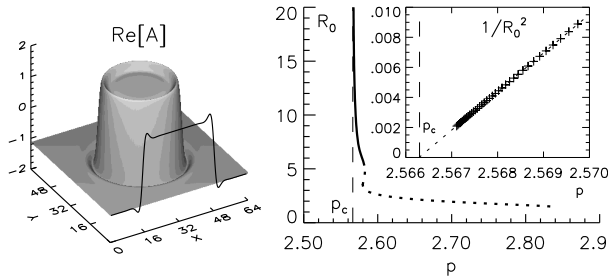


FIG. 2. Left: Spatial dependence and transverse section of a SD for the PCGLE. Right: Radius of SD (solid line) and LS (dotted line) as a function of the forcing for the PCGLE. The inset shows the linear dependence of $1/R_0^2$ with p close to the bifurcation point as predicted by (12).

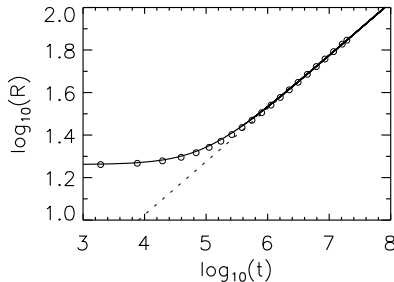


FIG. 3. Growth of a circular domain as function of the time at $p = p_c$. The symbols correspond to the numerical integration of Eq. (1), the solid line is the theoretical prediction (9) with $c_3 = 0.3129$ calculated from (11) and the dotted line has a slope $1/4$ showing the asymptotic behavior.



FIG. 4. Evolution of an arbitrarily shaped domain at $p = p_c$. From left to right: $t=0$, $t=2400$, $t=80000$ and $t=1650000$.

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